



DEPARTMENT OF ECONOMICS AND BUSINESS
AARHUS UNIVERSITY

Ranking paths in stochastic time-dependent networks

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VeRoLog - June 18-20, 2012





Agenda

Stochastic time-dependent networks

- Assumptions

- A hypergraph representation

- Route choice in STD networks

- Route selection criteria

- Example MEC (time-adaptive routing)

Ranking paths

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- Ranking paths in a STDN

- Example (continued)

Computational results



Stochastic time-dependent networks

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- Departure and arrival times at nodes are integer.



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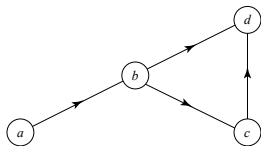
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- ▶ No waiting allowed at nodes (arrival = departure).



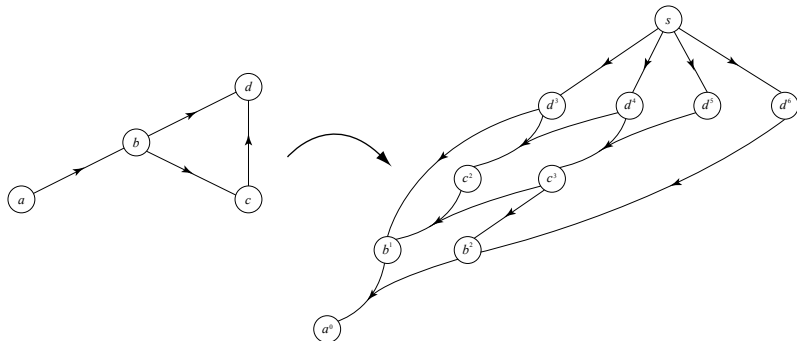
A hypergraph representation

$(u, v), t$	$(a, b), 0$	$(b, c), 1$	$(b, c), 2$	$(b, d), 1$	$(b, d), 2$	$(c, d), 2$	$(c, d), 3$
$l(u, v, t)$	$\{1, 2\}$	$\{2, 3\}$	$\{3\}$	$\{3\}$	$\{6\}$	$\{3, 4\}$	$\{4, 5\}$
p_{ijt}	$\{\frac{1}{2}, \frac{1}{2}\}$	$\{\frac{1}{2}, \frac{1}{2}\}$	$\{1\}$	$\{1\}$	$\{1\}$	$\{\frac{1}{2}, \frac{1}{2}\}$	$\{\frac{1}{2}, \frac{1}{2}\}$



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Route choice in STD networks

A **routing strategy** between an origin o and a destination d when leaving the origin at time zero assigns to each node and possible leaving time and successor arc.



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In this talk we consider a priori routing



Route selection criteria

We consider the following objectives:

- ▶ Minimizing the expected travel time (MET)

Under MEC we define the following costs:

- ▶ $c(u, v, t)$ – cost of leaving node u at time t along arc (u, v) .
- ▶ $g(t)$ – penalty cost of arriving at node d at time t .



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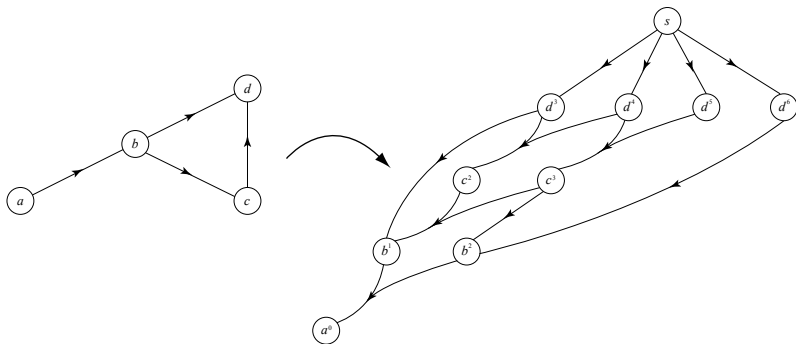
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Known results

- ▶ Time-adaptive route choice – Finding the best strategy $\Leftrightarrow$ finding a minimum weight hyperpath.
- ▶ A priori route choice – Finding the shortest path is NP-hard.

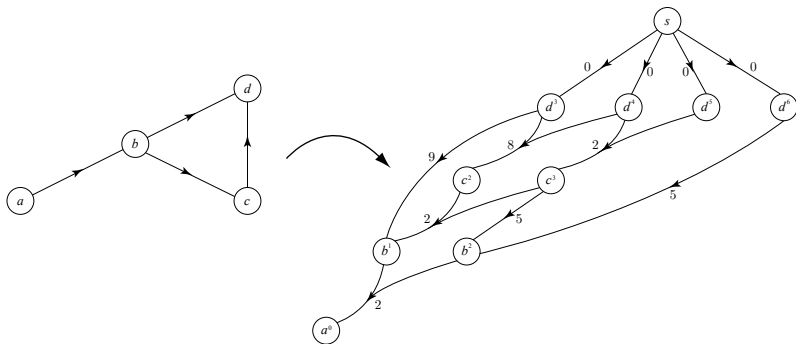


Example MEC (time-adaptive routing)



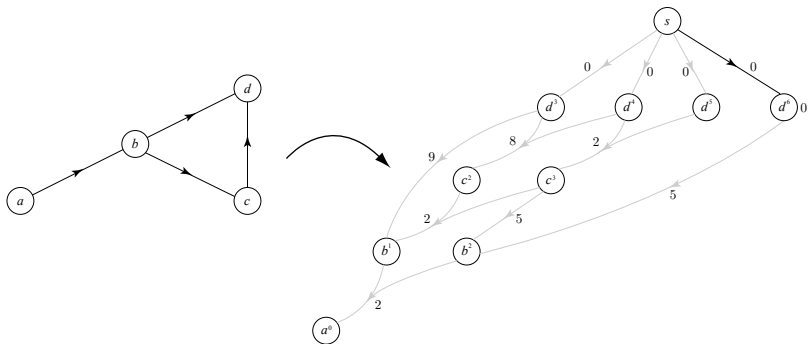


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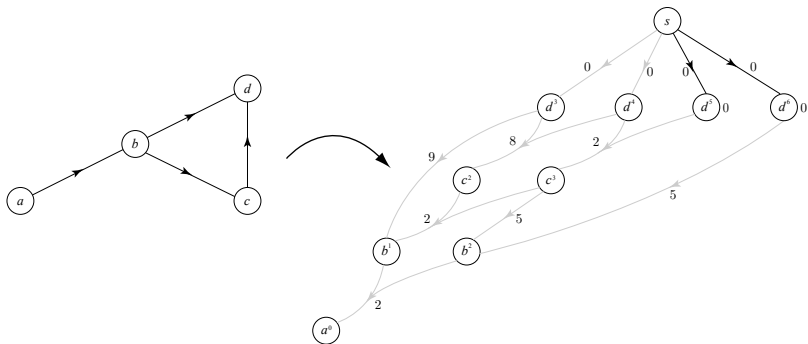


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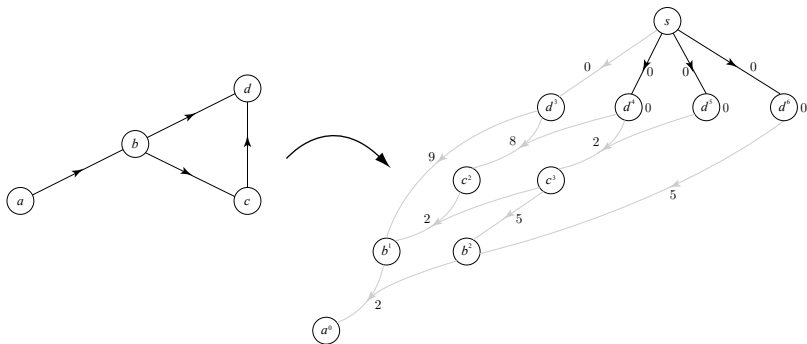


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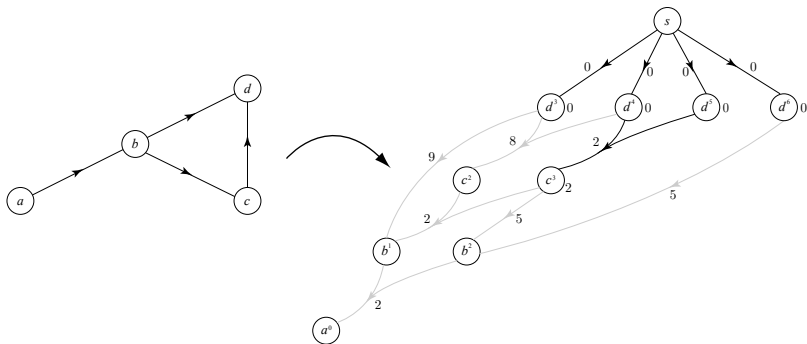


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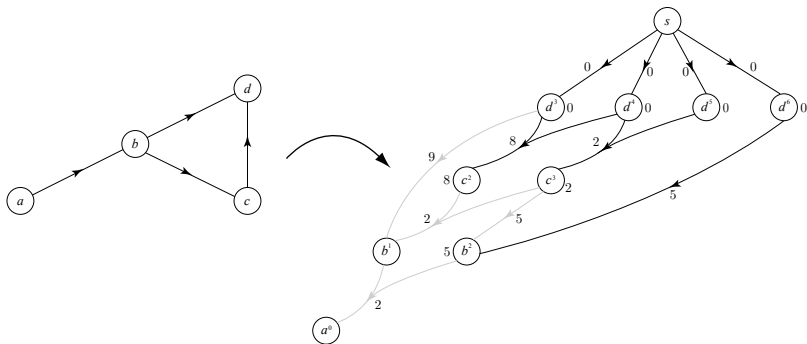


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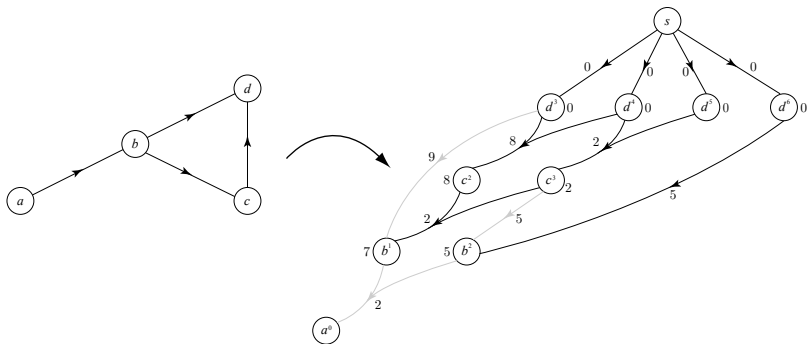


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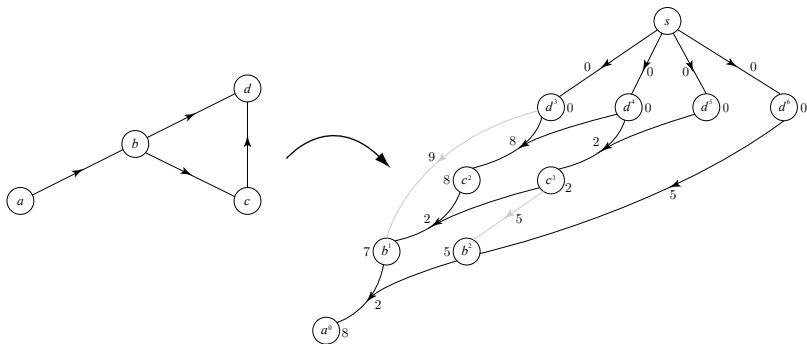


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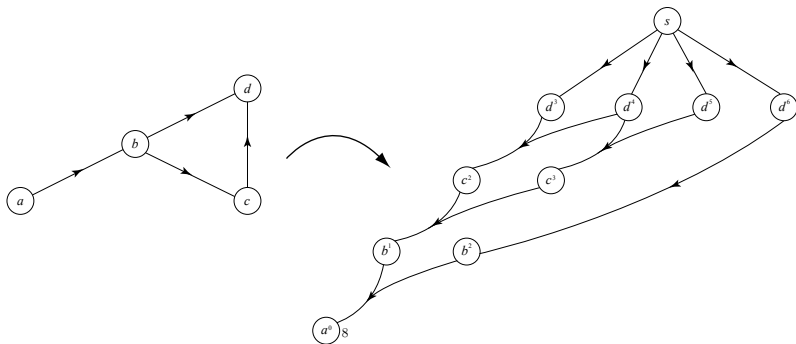


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Ranking scheme (deterministic case)

Let $\mathcal{P}$ denote the set of paths in G and p the shortest path.

Generic ranking scheme based on lower bounds:

1. Partition $\mathcal{P} \setminus \{p\}$ into q disjoint subsets $\mathcal{P}^1, \dots, \mathcal{P}^q$ based on p



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5. Output $(\hat{w}^i, p^i)$ and repeat using p^i and $\mathcal{P}^i$



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- ▶ Finding the best routing strategy gives us a lower bound on the expected cost of the shortest path
- ▶ The best routing strategy may be used to partition the solution space



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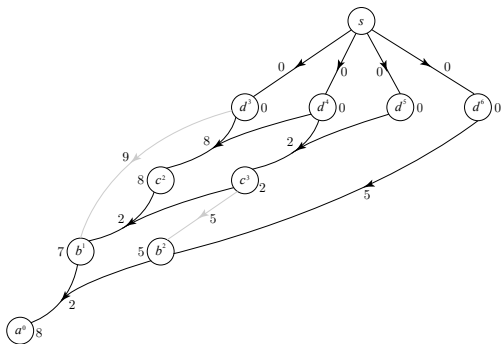
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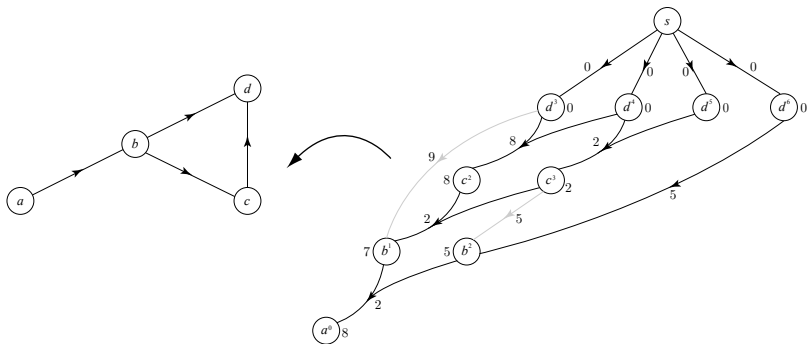


Optimal routing strategy



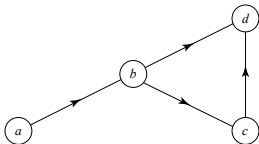


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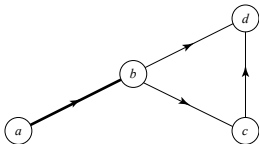


Choosing subpath



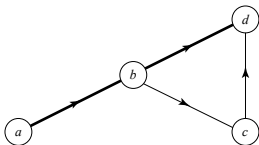


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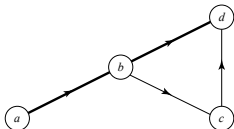


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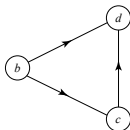
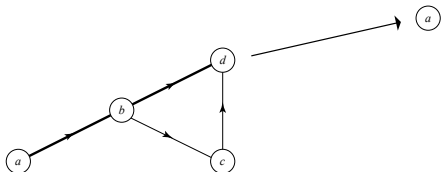


Disjoint subsets (subgraphs)





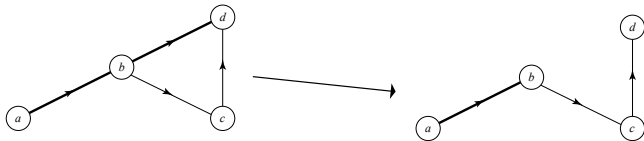
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$\mathcal{P}^1$



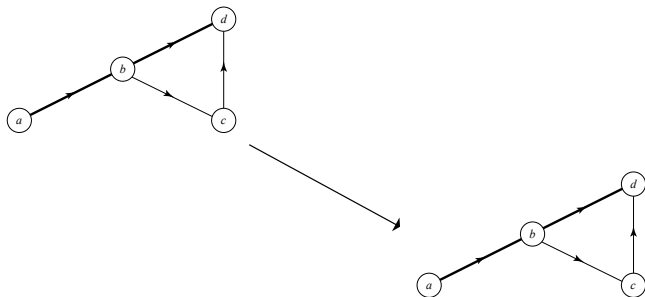
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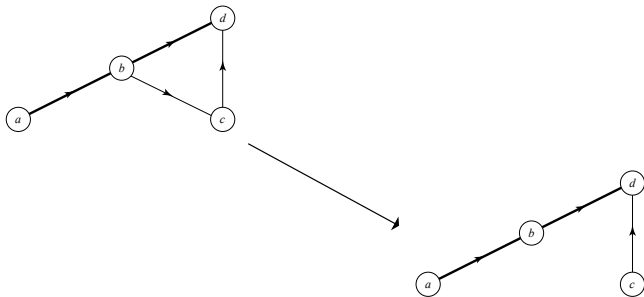
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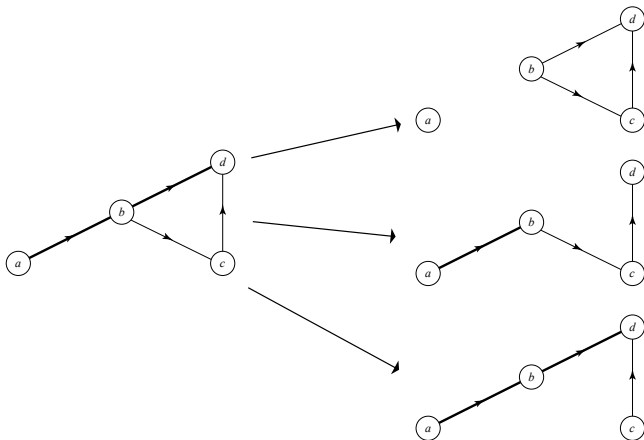
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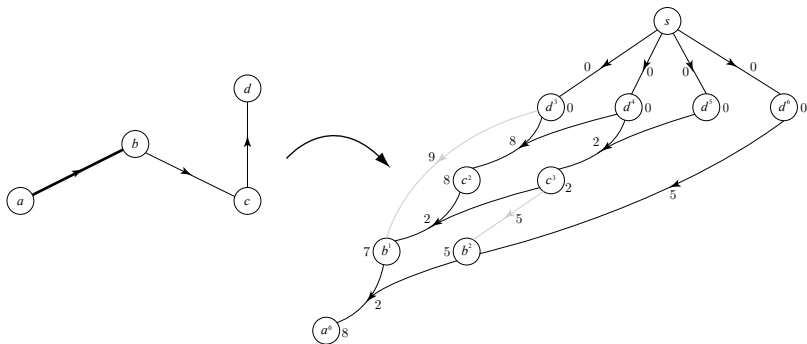


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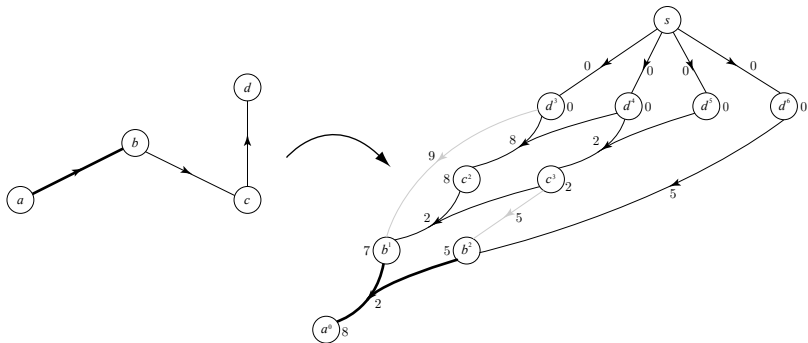


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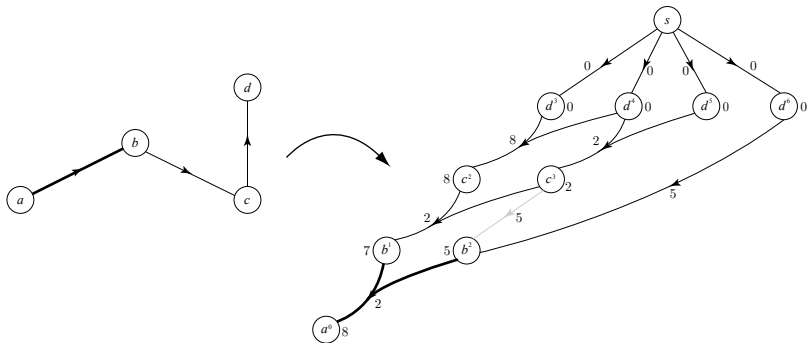


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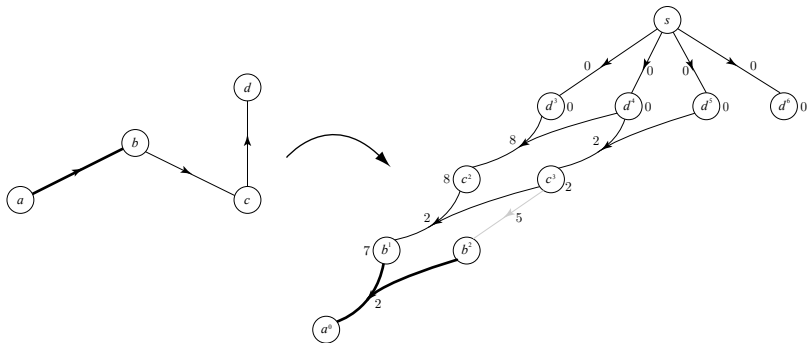


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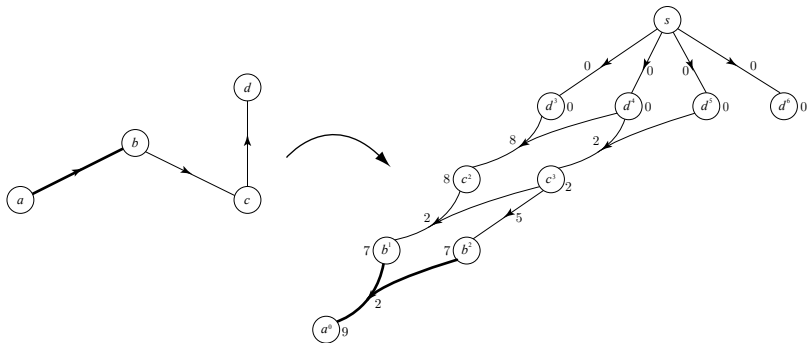


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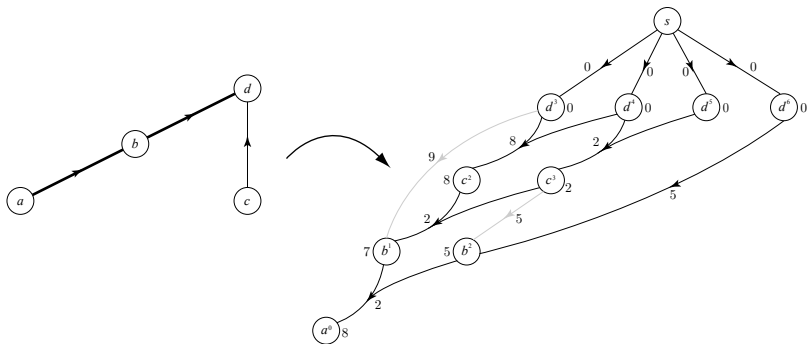


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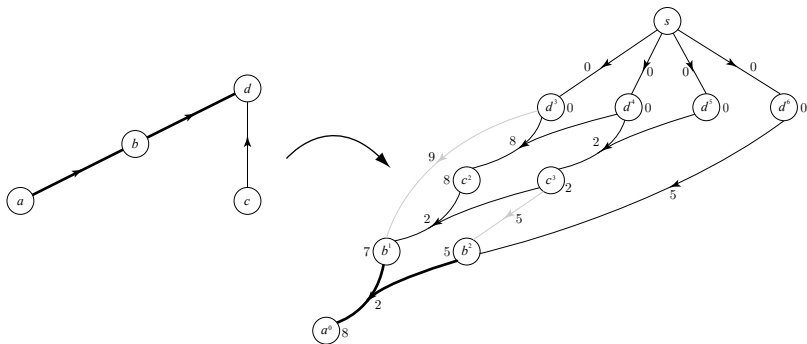


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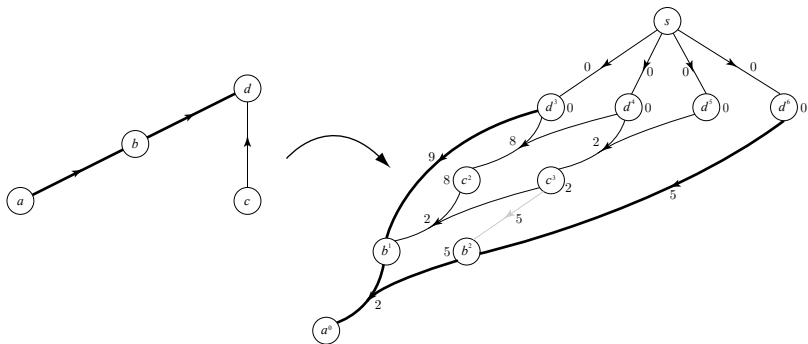


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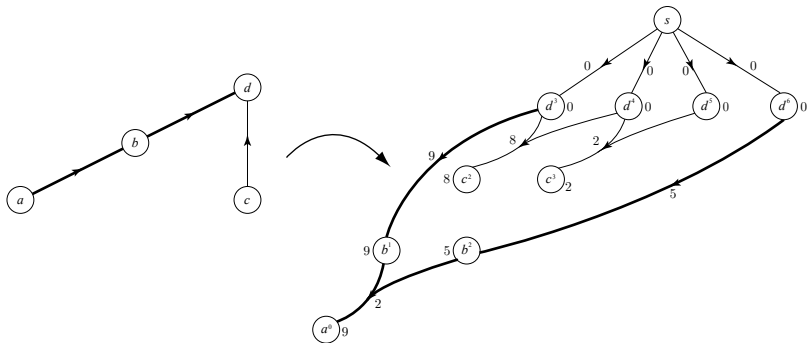


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- Example MEC (time-adaptive routing)

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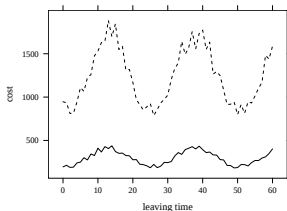


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- ▶ Off-peak costs [1, 1000] (100% increase in peaks) + random noise (10%).





Test instances

Class	peak dependent costs			random costs		
	1	2	3	4	5	6
Grid size	5×10	10×10	20×10	5×10	10×10	20×10
n	2320	7573	21454	1497	3961	11856
m	7809	27278	79570	5056	14295	43991
H	118	156	237	75	101	155

Results ($K = 100$)

Class	ite_K	CPU_K	ite_1	CPU_1	$\delta(u) = 1$	$\delta(u) = 2$	$\delta(u) = 3$	$\delta(u) = 4$	inc	inc_{S-PS}
1	356	8	13	0.3	82	14	4	1	49	5
2	454	37	11	1.0	82	14	4	0	17	7
3	2359	875	133	53.5	85	13	2	0	10	5
4	1427	25	133	2.5	50	25	20	5	18	43
5	9942	564	2722	157.9	39	21	27	12	8	54
6	203479	34227	89519	15127.5	25	16	27	31	3	59



Questions



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