

# Methods for Sensor Based Farrowing Prediction and Floor-heat Regulation

## The Intelligent Farrowing Pen

Ph.D. Dissertation

Aparna U.

Dept. of Animal Science  
Aarhus University  
Denmark

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## Objective

To develop and validate an automated system that

- monitors the pre-parturition behaviour of the sow in the farrowing pen,
- predicts the onset of farrowing
- would further help the farm manager to optimize the decisions related to parturition and post-parturition - e.g. optimal floor-heat regulation system

by integrating several sensor information

## purpose

"to reduce the piglet mortality"

\*Study was supported by The Danish National Advanced Technology Foundation

# Overview of the Study

Herd Level Computer

Sensor  
Observations

Herd  
Database

Prediction  
Algorithm

at the pen level

# Overview of the Study

Herd Level Computer

Sensor  
Observations

Herd  
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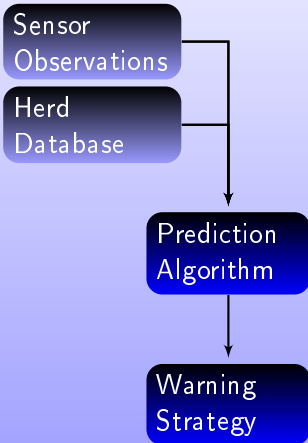
Prediction  
Algorithm

Warning  
Strategy

at the pen level

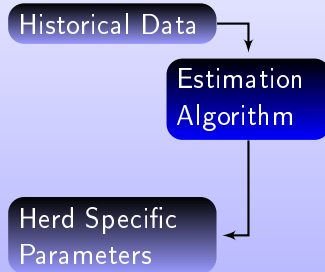
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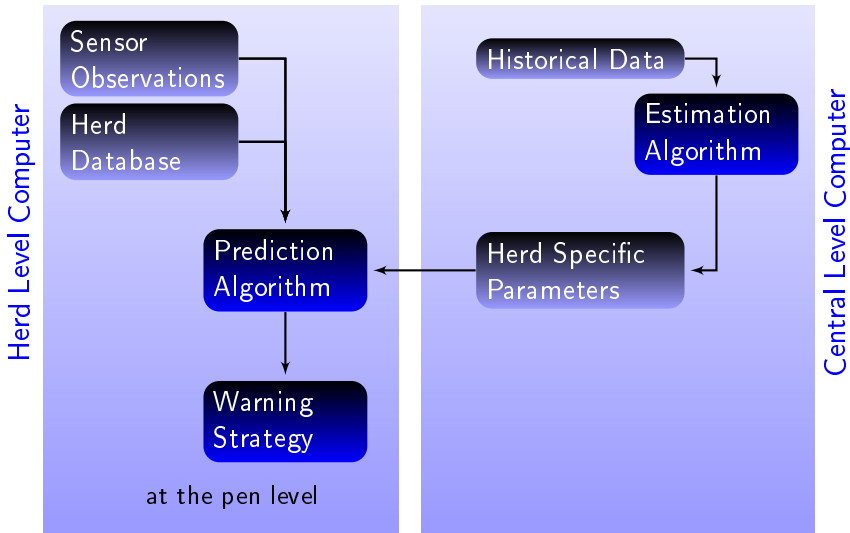


at the pen level

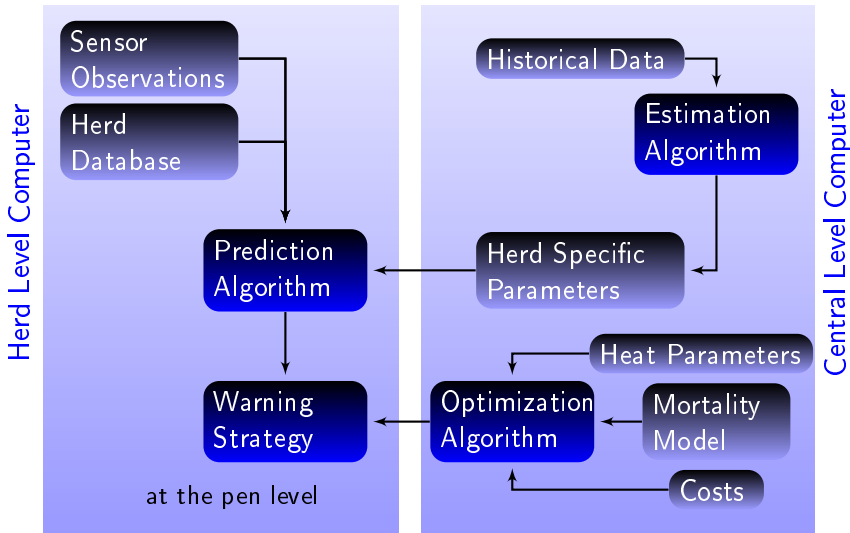
Central Level Computer



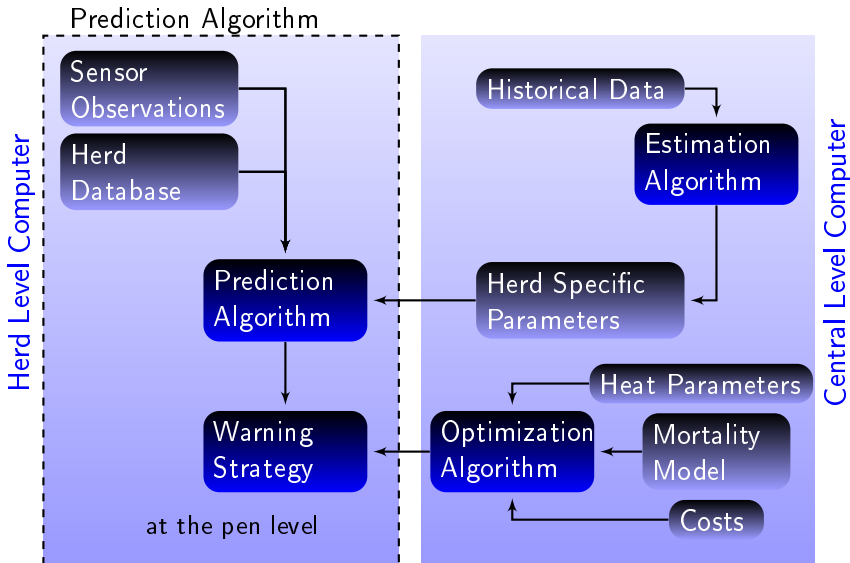
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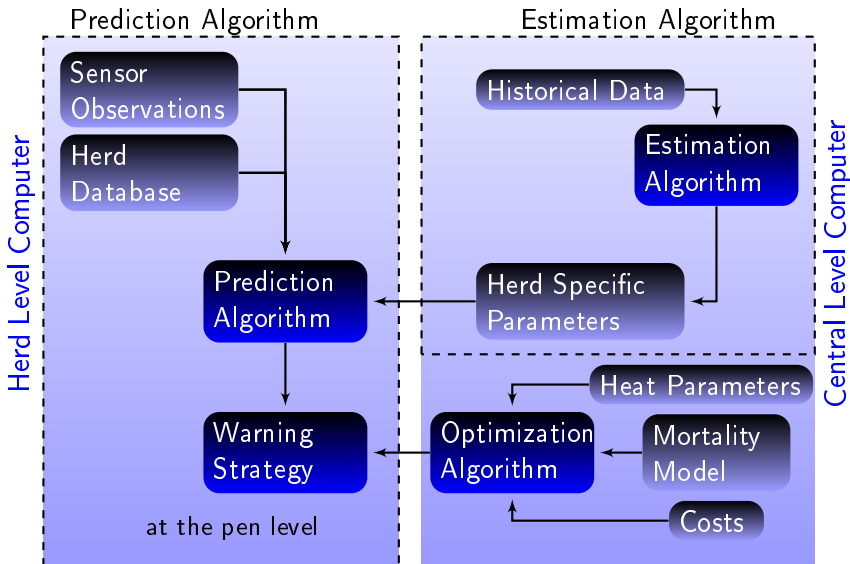


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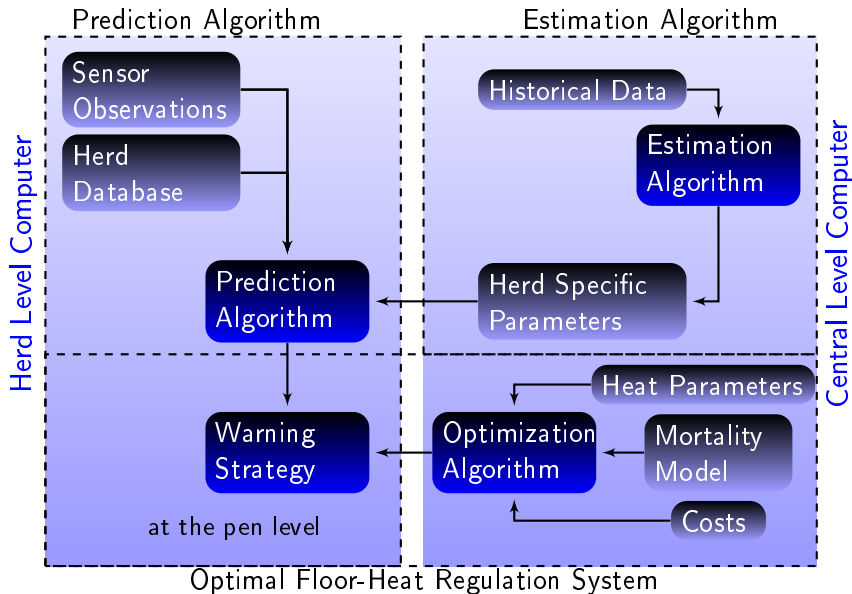




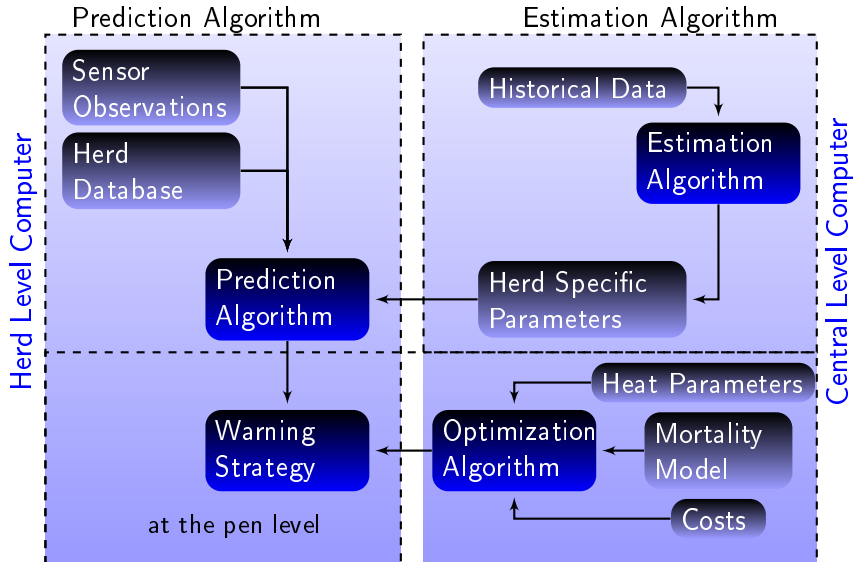
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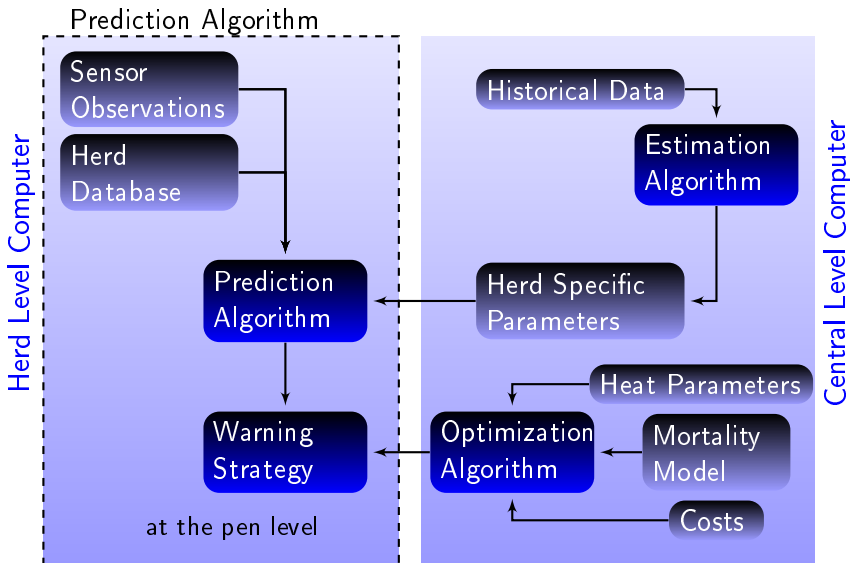


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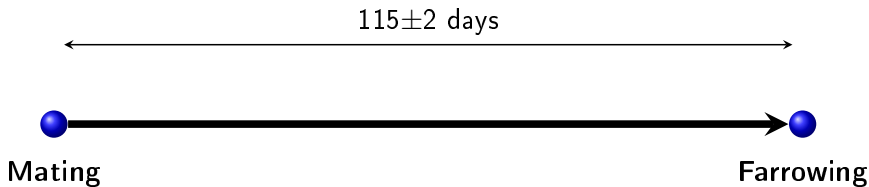
Optimal Floor Heat Regulation System

# Overview of the Study



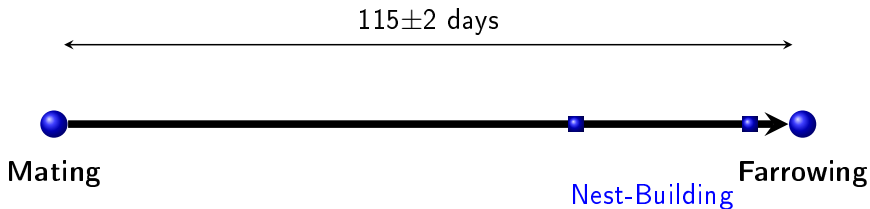
# Gestation Period

## Behavioural States



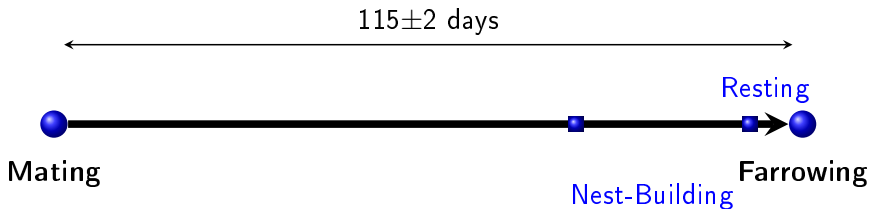
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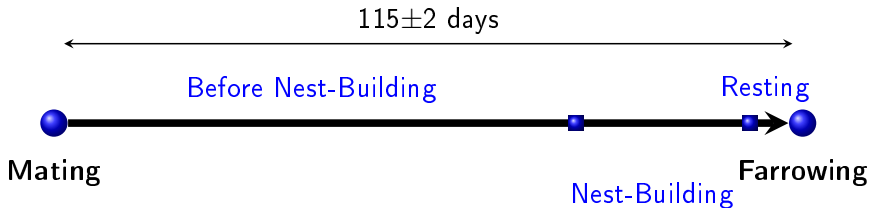
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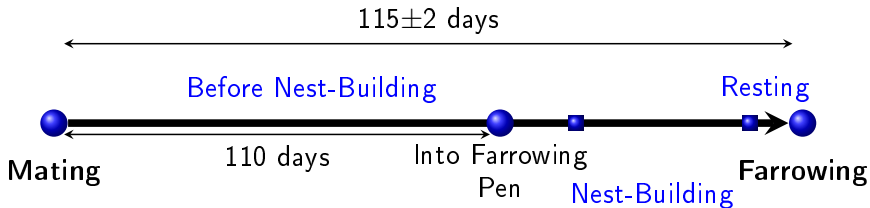
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## Behavioural States



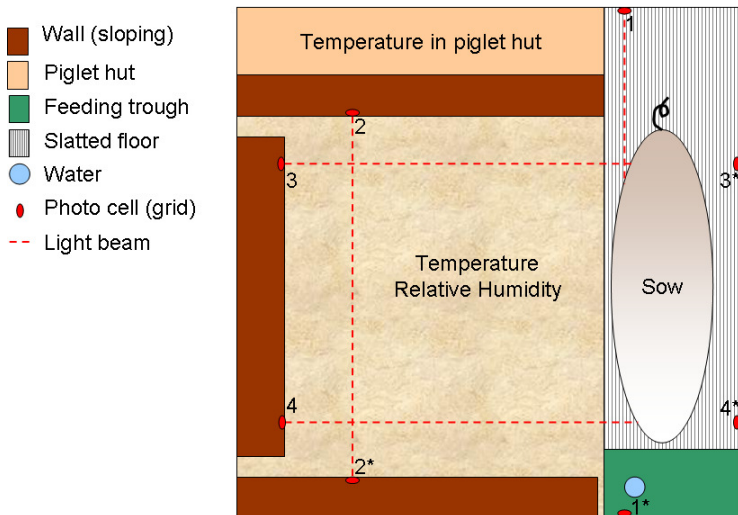
# Farrowing Pen

Number of sows observed: 64



# Sensor set-up at the pen level

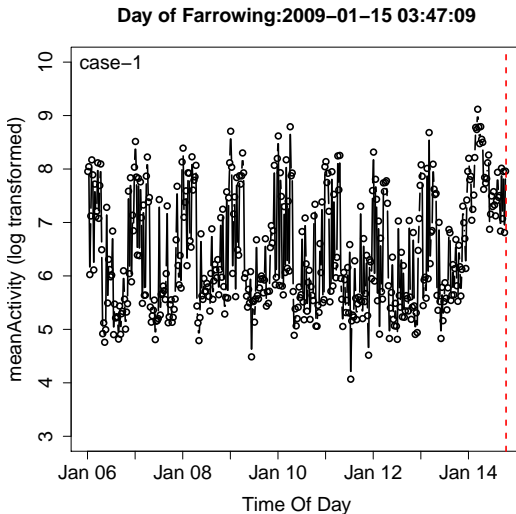
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# Online Recording of Sensor Observation for a Sow - An idea

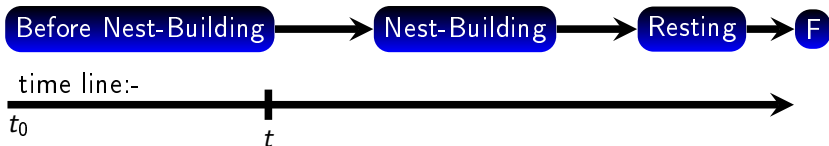
## Water consumption

# Sensor observation for a sow - meanActivity



# "Farrowing process" as a Markov Model

Farrowing process - continuous time

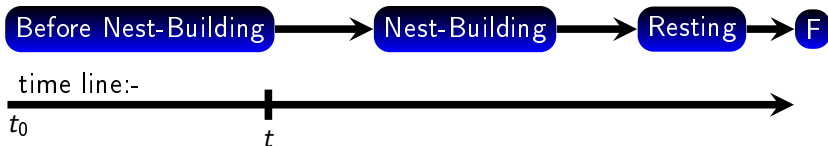


$T_t$ : remaining time to onset of farrowing

✓ Stochastic process

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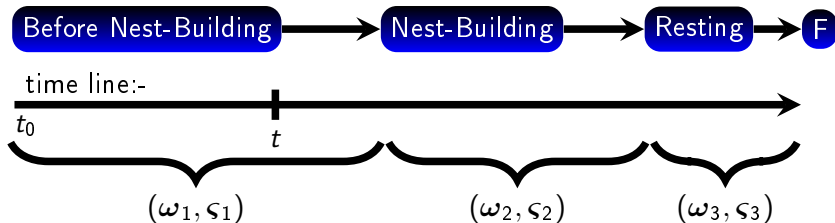
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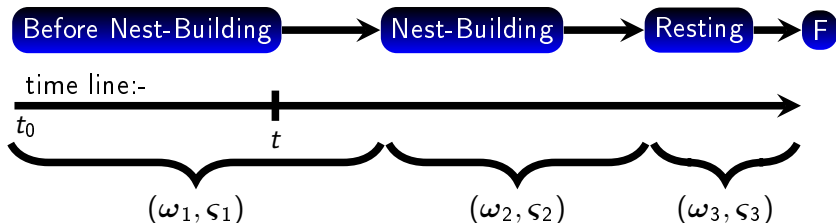
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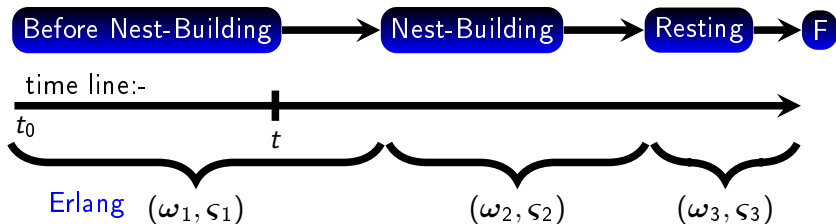
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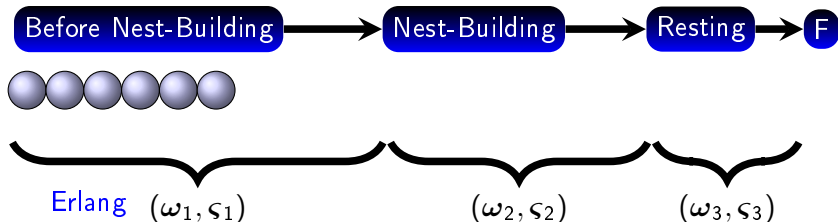
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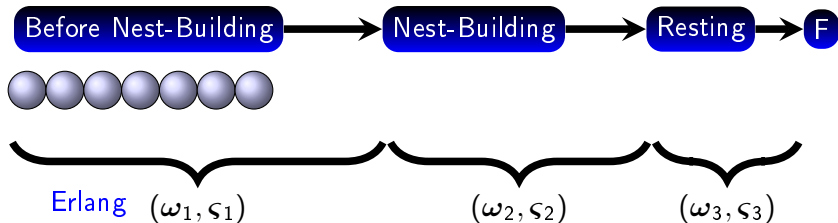


States into smaller divisions -> "Behavioural Phases"

'phases' reflect the time since mating

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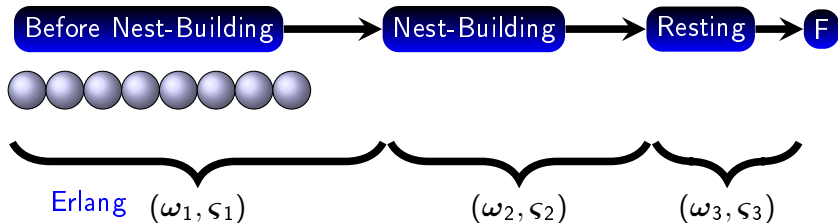


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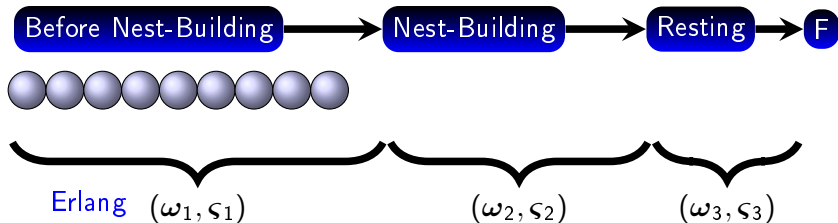


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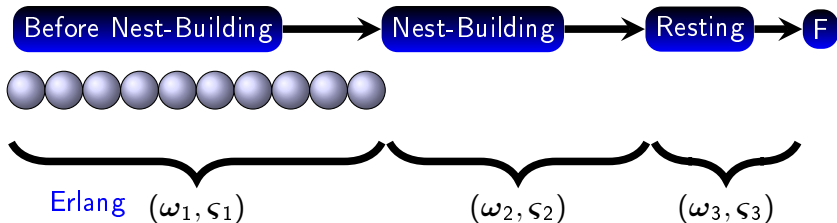


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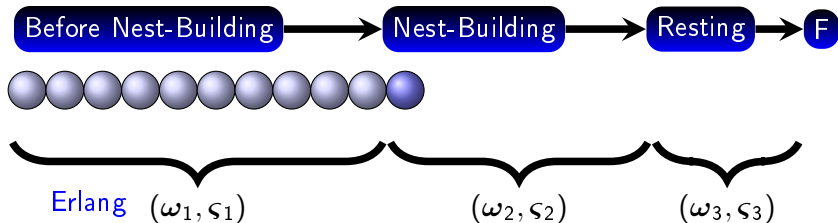


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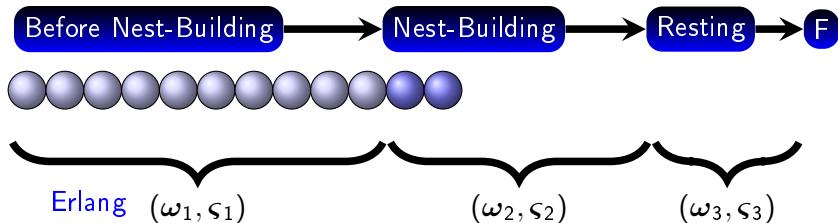
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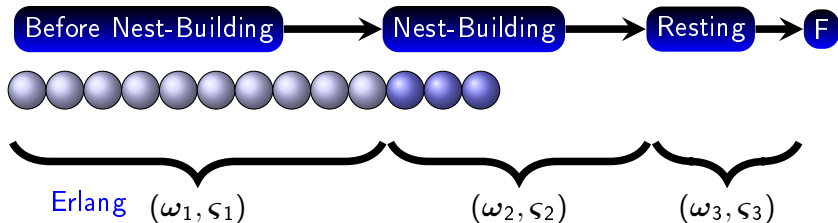


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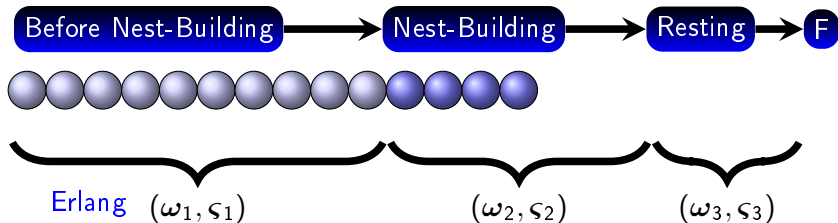


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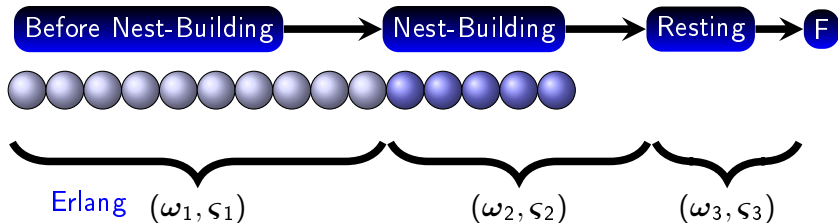


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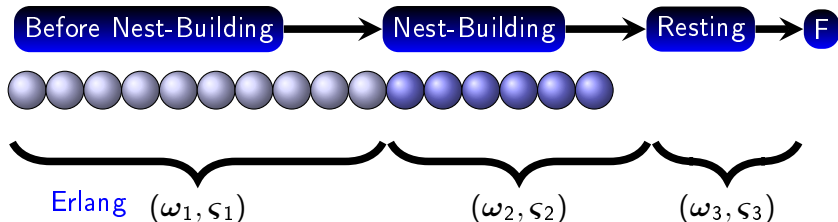


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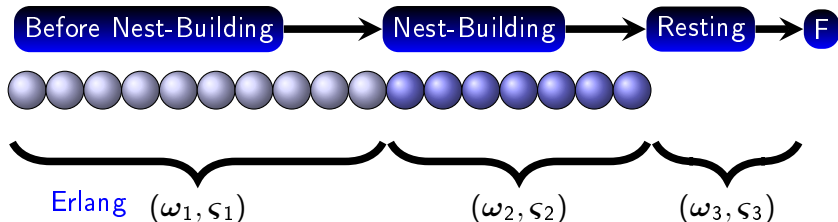


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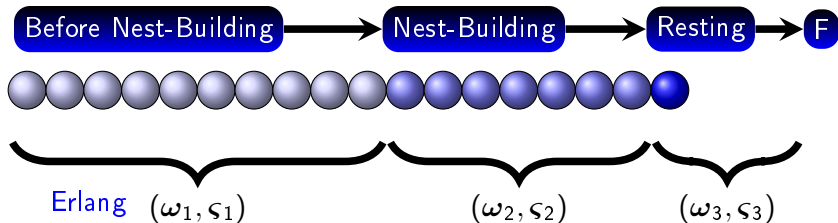


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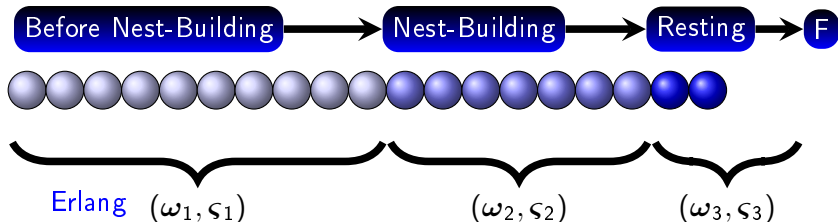


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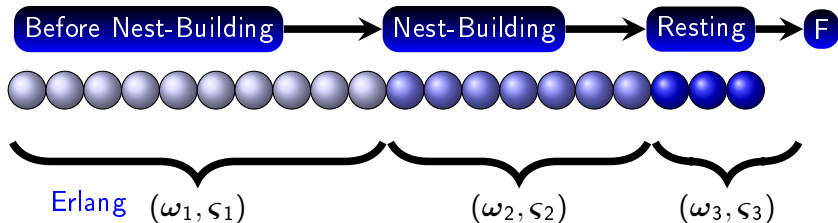
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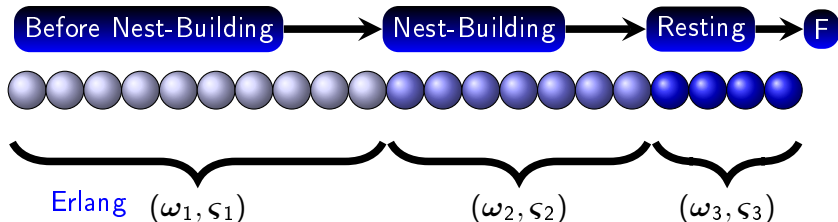


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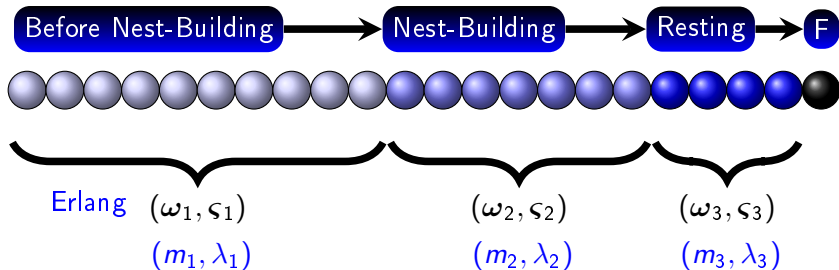


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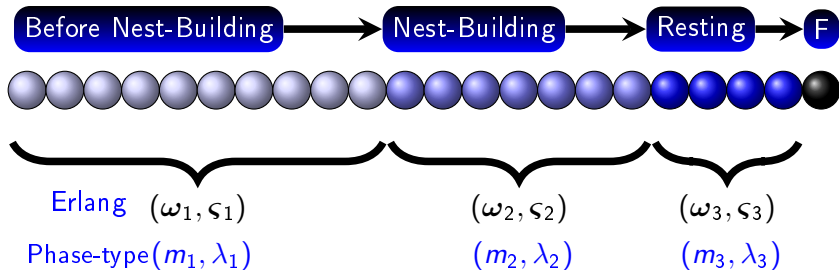


~~'semi'~~

Markov Process over phases

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Farrowing process - continuous time



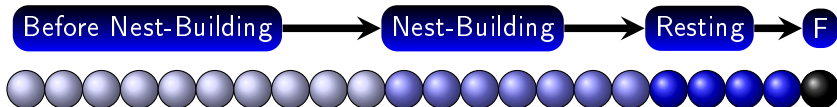
~~'semi'~~

Markov Process over phases

Convolution of three Phase-type distributions

# Farrowing and Prediction Process

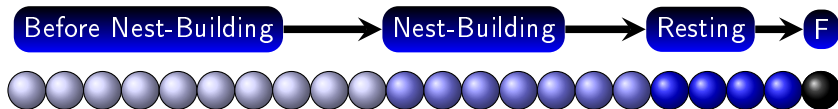
Farrowing process - continuous time



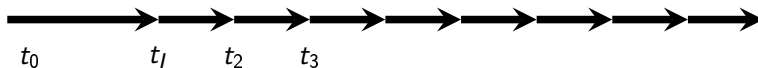
'Markov Model'

# Farrowing and Prediction Process

Farrowing process - continuous time



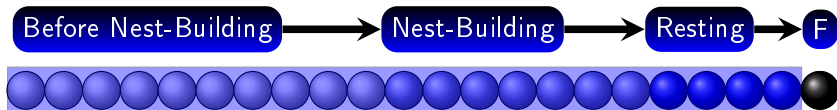
Prediction process discrete time points



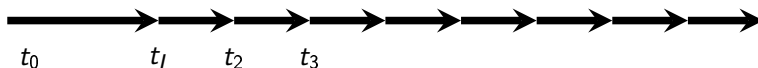
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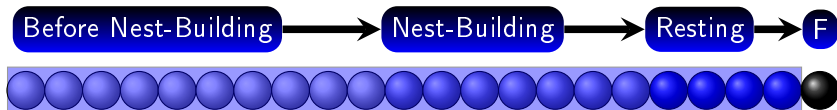
$\alpha_t$  : distribution of phases

'Hidden' + 'Markov Model'

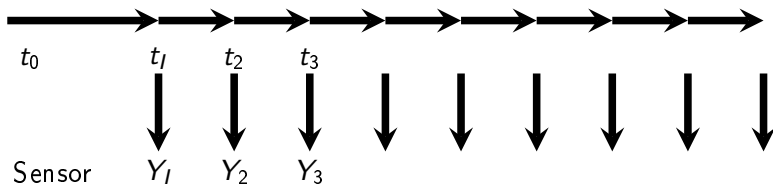
$T_t$  : time to onset of farrowing  $\sim PH(\alpha_t, \mathbf{S})$

# Farrowing and Prediction Process

Farrowing process - continuous time



Prediction process discrete time points



$$\Pr(Y_t | \text{Phase}_t)$$

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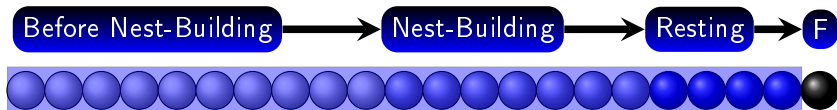
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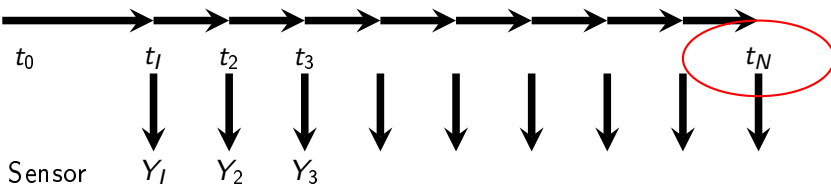


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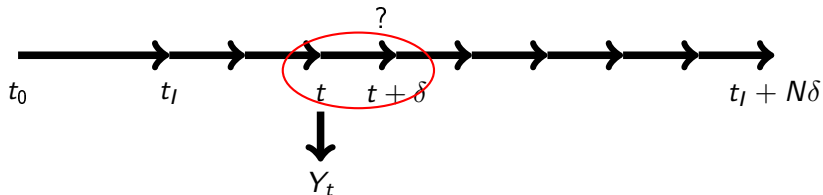
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# Prediction of Onset of Farrowing



$\alpha_{t+\delta}$ : distribution of phases in the **next** prediction point

## Prediction of $\alpha_{t+\delta}$

At each prediction point,

- ① calculates  $\alpha_{t+\delta}$  using **time transition** (Markov chain)
- ② updates  $\alpha_{t+\delta}$  using the **sensor information**

# Prediction of Distribution of Phases $\alpha_{t+\delta}$

# Prediction of Onset of Farrowing

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$T_{t+\delta}$ : *time to onset of farrowing*  $\sim PH(\alpha_{t+\delta}, \mathbf{S})$

## Statistical measures...

- Expected time to onset of farrowing

# Prediction of Onset of Farrowing

## Prediction of $\alpha_{t+\delta}$

At each prediction point,

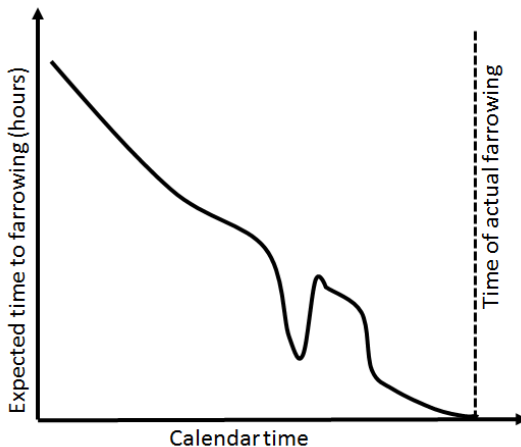
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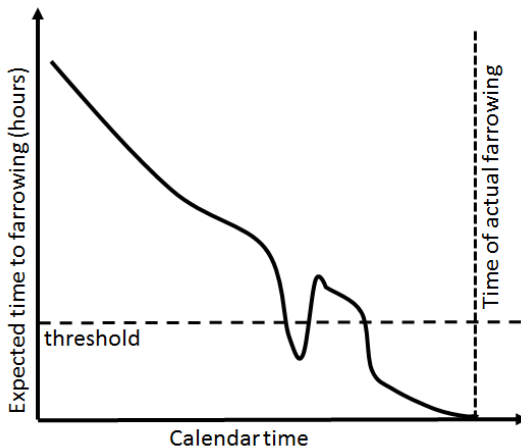
## Statistical measures...

- Expected time to onset of farrowing
- Probability of onset of farrowing in 12 hours

# Validating the Prediction - how???



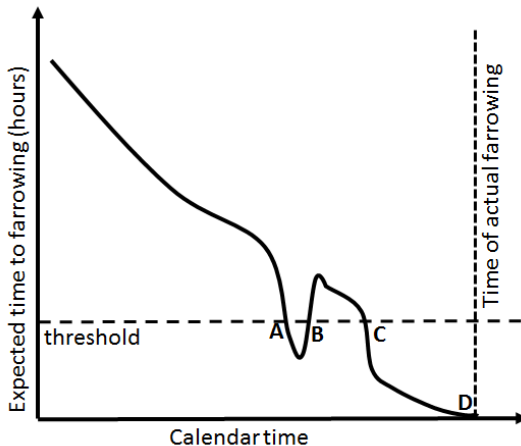
# Validating the Prediction - how???



# Online Prediction Curve - an example



# Warning periods - success Vs failure



# Example of False-warning Period

# Validating the Prediction Algorithm

Sensor	Sample size	True Warnings %	Warning Dur. (hours)		Error (hours)
			Mean	SD	
Water	38	21	11.7	2.2	3.4
Video	55	98	14.4	12.5	1.6
Water-Video	35	97	11.5	4.6	0.7

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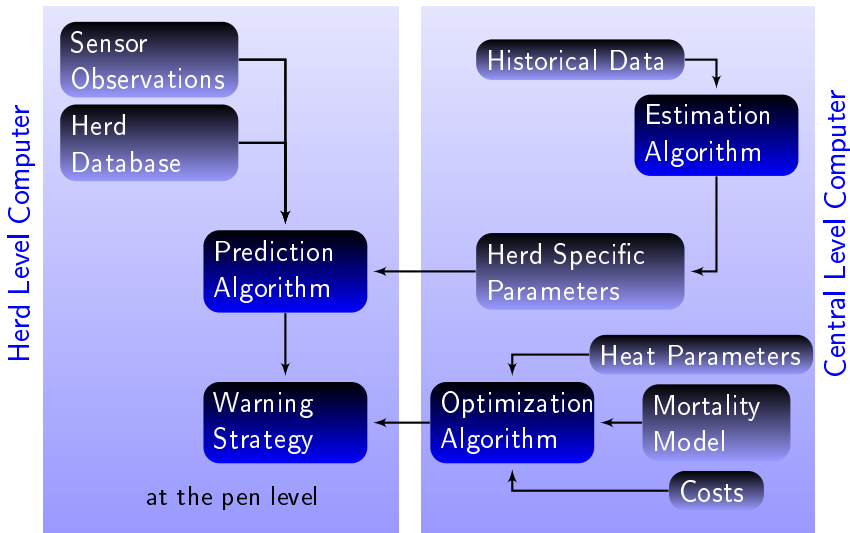
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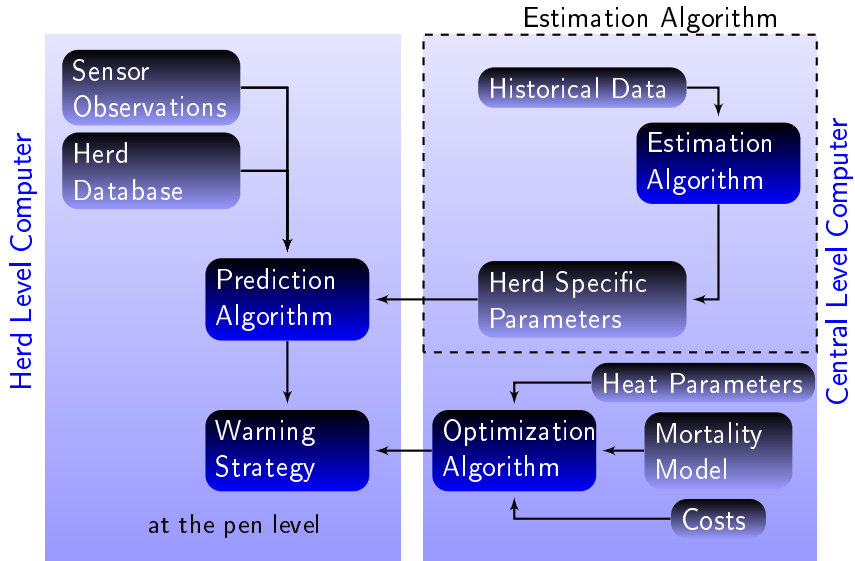
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# Estimation of HPMM Parameters

by maximizing the likelihood function



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Stochastic Expectation-Maximization algorithm (SEM algorithm)

-iterative method

- Uses time of mating and farrowing information in addition to sensor information
- Phases are allocated by weighted sampling - Stochastic

# Estimated Sojourn time distribution

Behavioural State	Duration (hours)		Number of Phases	Rate (per hour)
	Mean	SD		
Before Nest-Building	751.20*	29.58	645	0.86
Nest-Building	17.02	0.80	458	26.91
Resting	0.53	0.22	6	11.40
Gestation period, days	117	1.2	1109	-

\*in addition to 85 days

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## Challenges with conditional model

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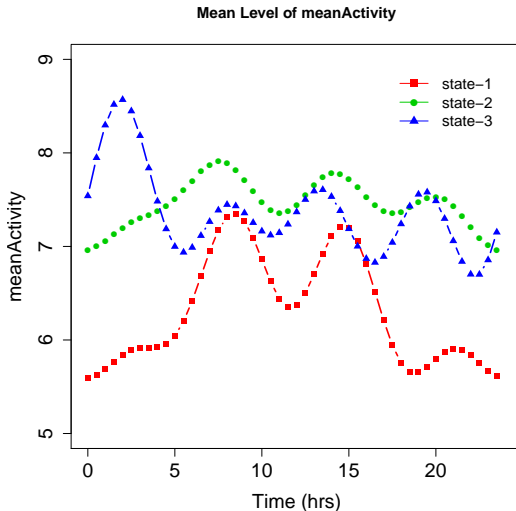
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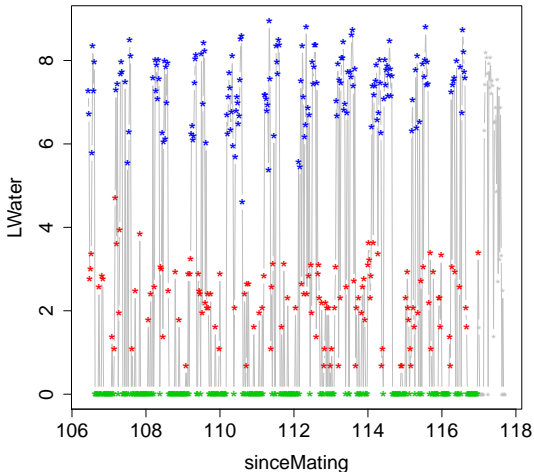
meanActivity - sdActivity - grid activity

- $\Pr(Y_t | \mathcal{S}_i) \sim \mathcal{N}(\mu_i^{(Y)}, \sigma_i^{2(Y)})_{\zeta}$
- Simple linear model
- sine-cosine functions - harmonic variables

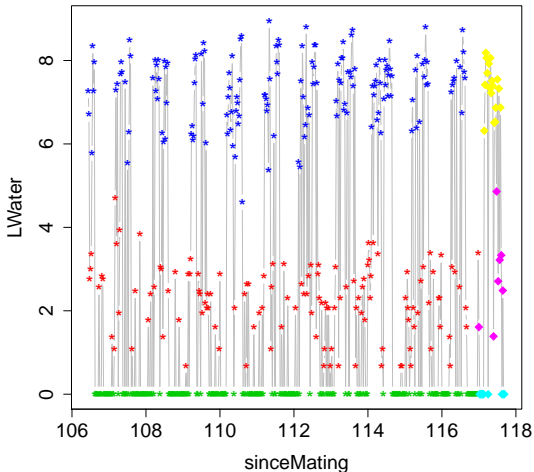
# Conditional Distribution of Sensor Observations



# Pattern of Water Consumption

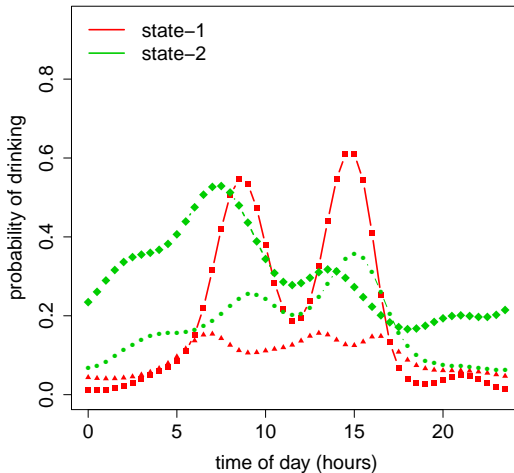


# Pattern of Water Consumption



# Probability of Water Consumption

at given time of day and state



# Estimation of HPMM Parameters

## Challenges with conditional model

- changing pattern with calender time - Behavioural Phases/States ✓
- diurnal rhythm conditioned on the Phase/State ✓
- model selection ✓
- dependency of the variables ?
- dependency on the phases ?

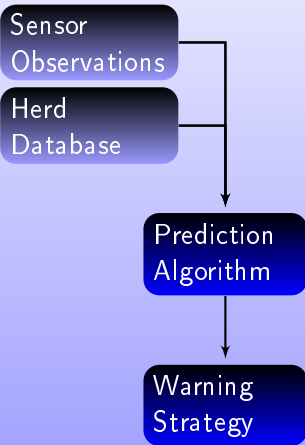
## Conclusion

- Duration of the *Nest-Building* state is similar to other studies
- Computational time - 26mins per iteration



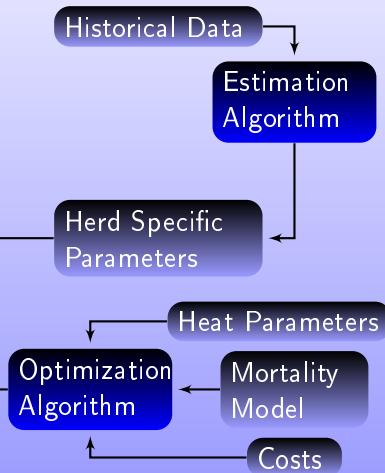
# Overview of the Study

Herd Level Computer

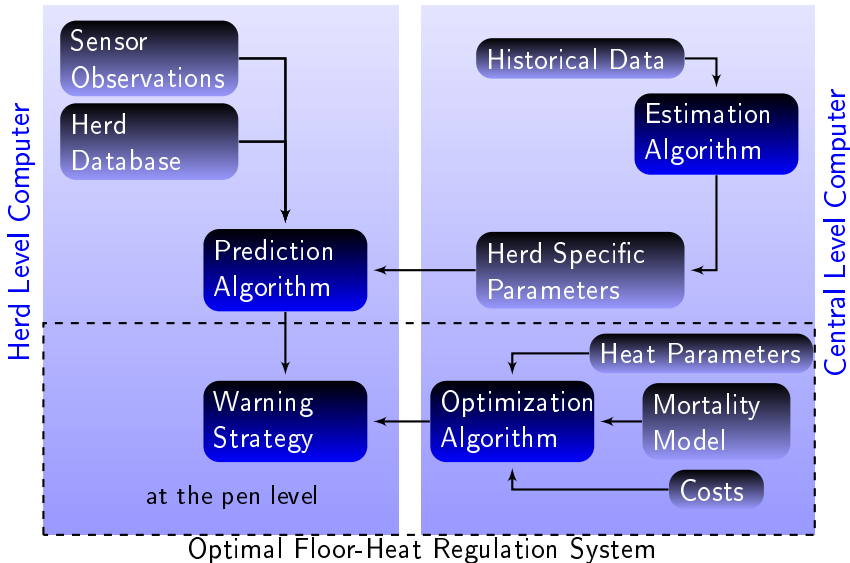


at the pen level

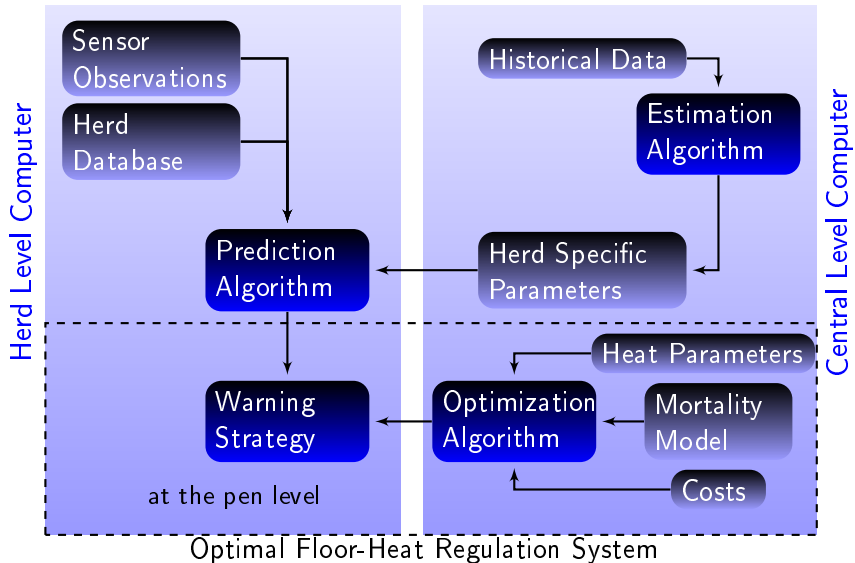
Central Level Computer



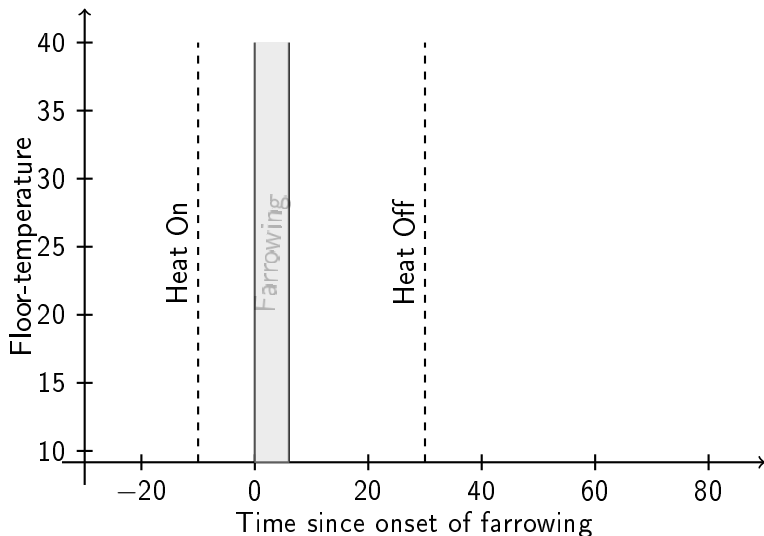
# Overview of the Study



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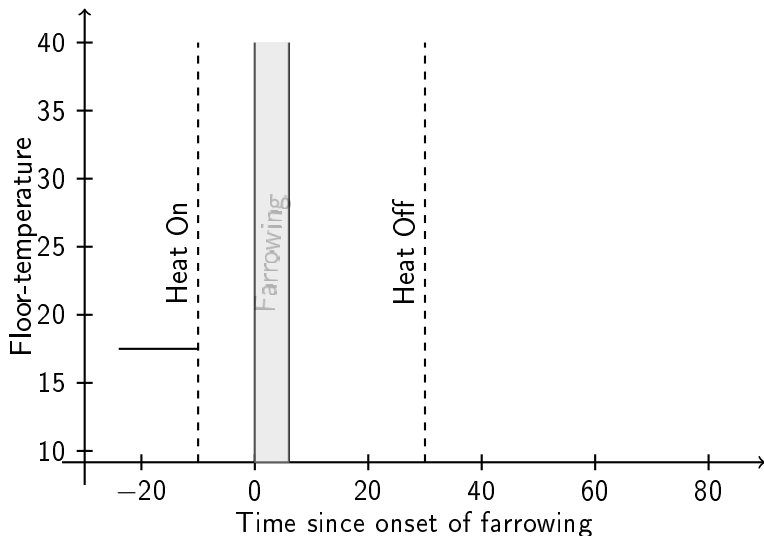


# Floor-heat Regulation on Pen Level



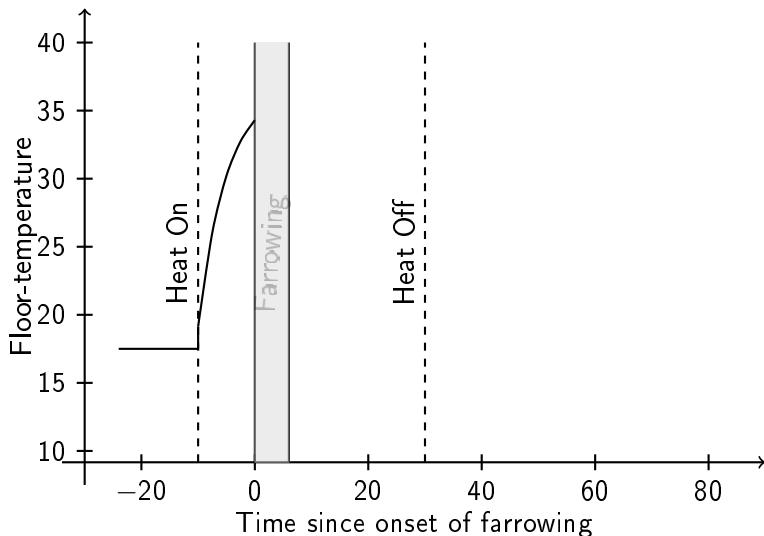
Malmkvist et. al. (2006) → survival of one extra piglet per litter

# Floor-heat Regulation on Pen Level



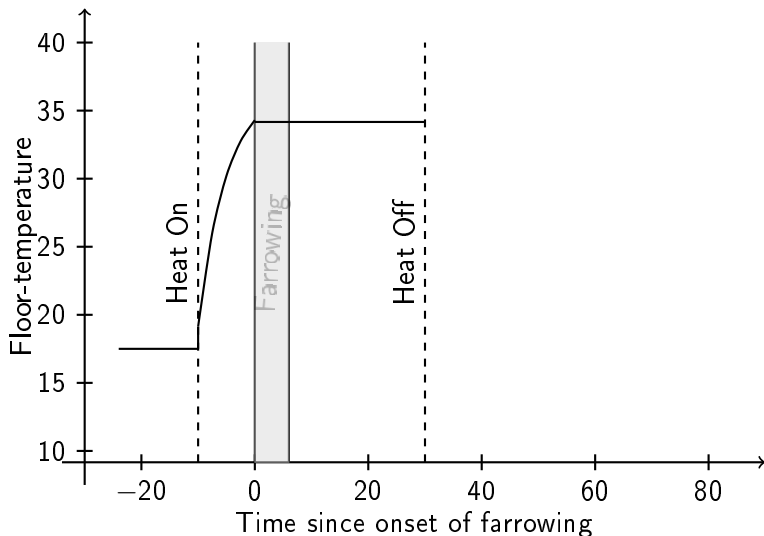
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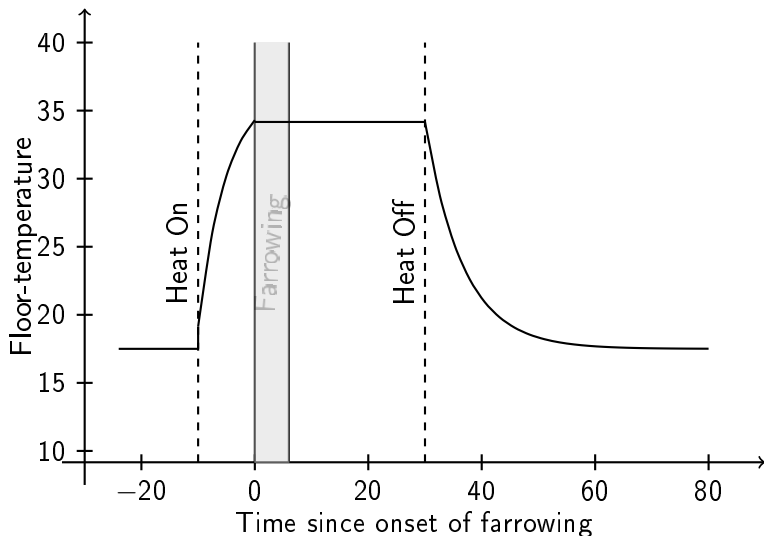
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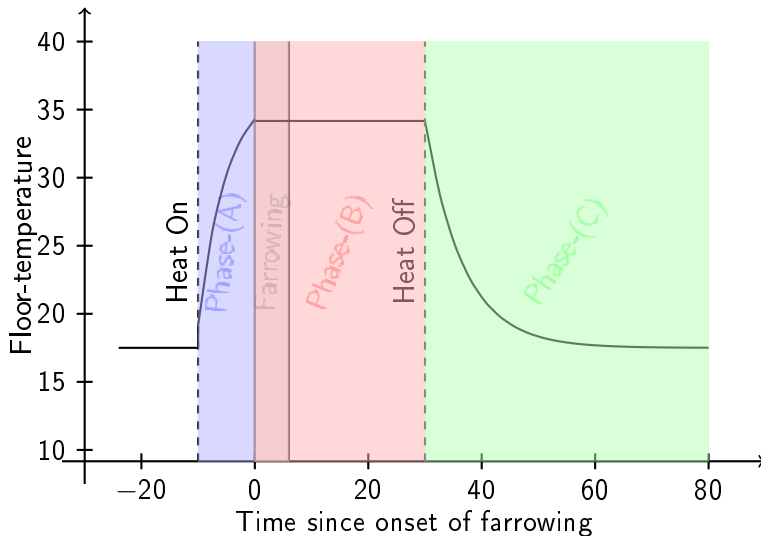
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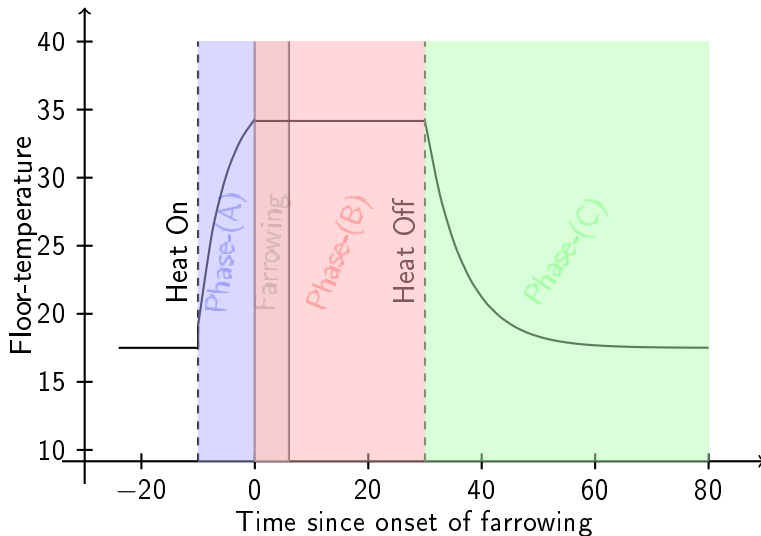


# Floor-heat Regulation on Pen Level



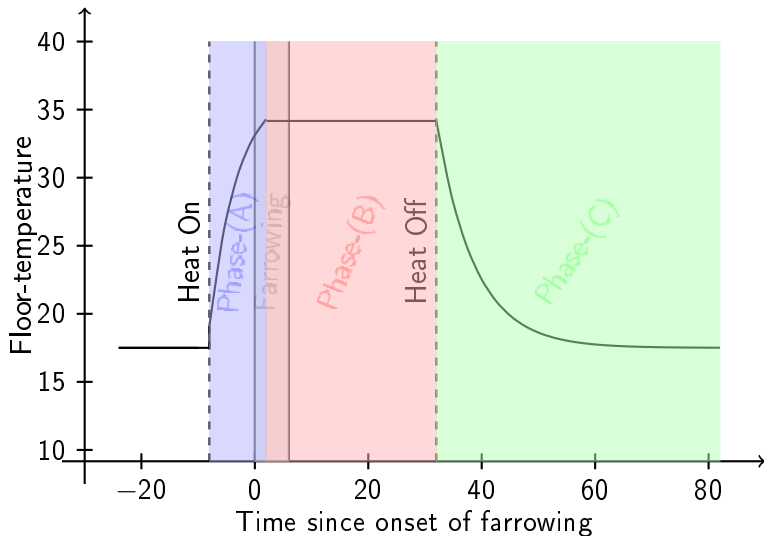
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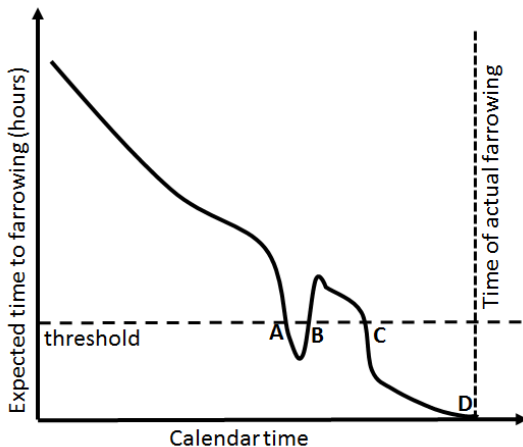


Malmkvist et. al. (2006) → survival of one extra piglet per litter

# Floor-heat Regulation on Pen Level



# How to choose threshold???



# Floor-heat regulation System

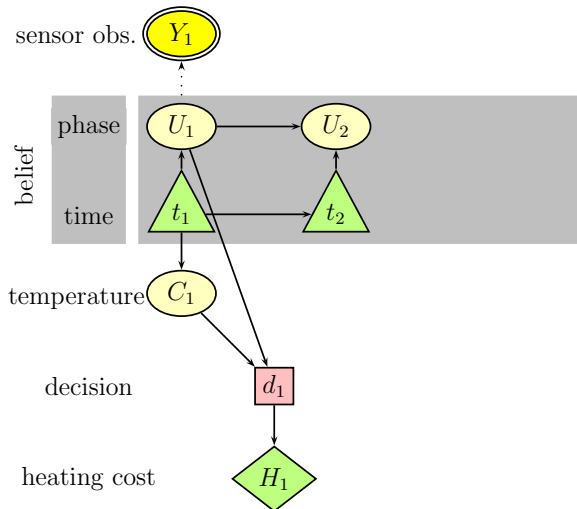
"Partially Observable Markov Decision Process (POMDP)"

# Floor-heat regulation System

"Partially Observable Markov Decision Process (POMDP)"

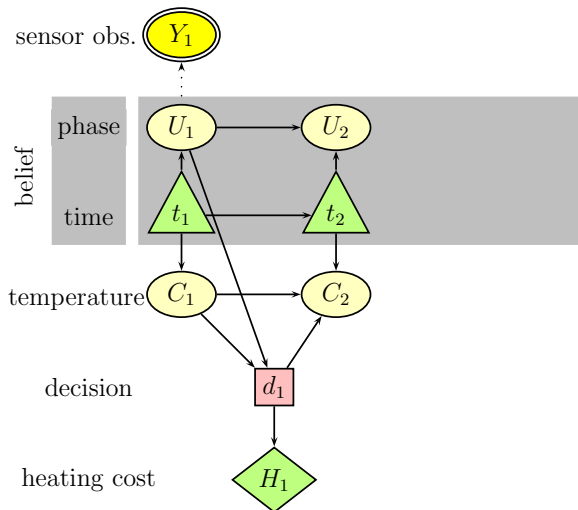
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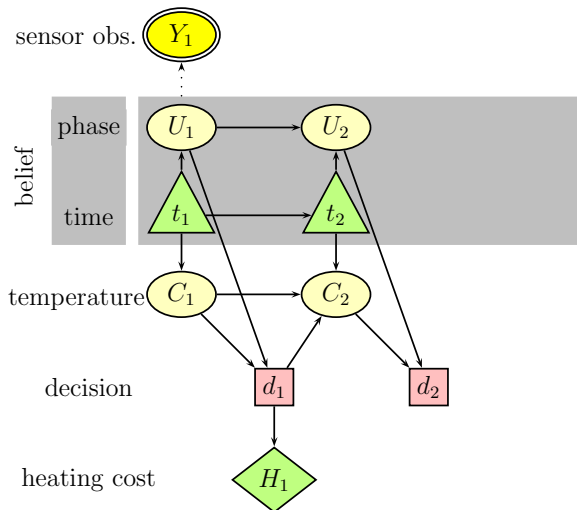
"Partially Observable Markov Decision Process (POMDP)"





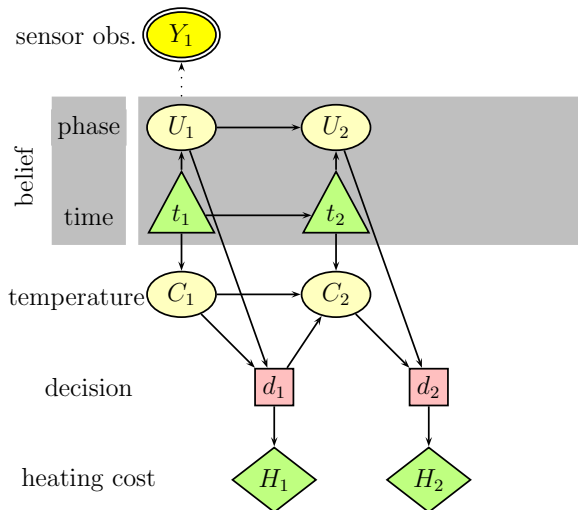
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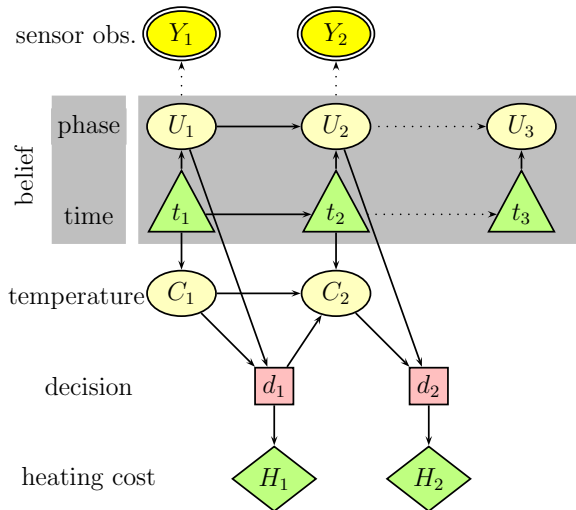
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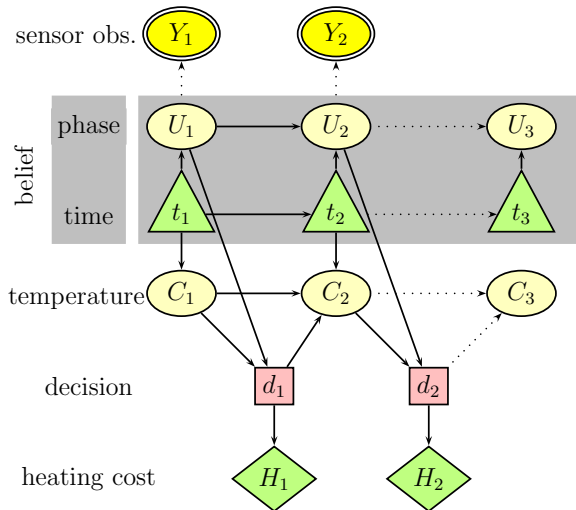
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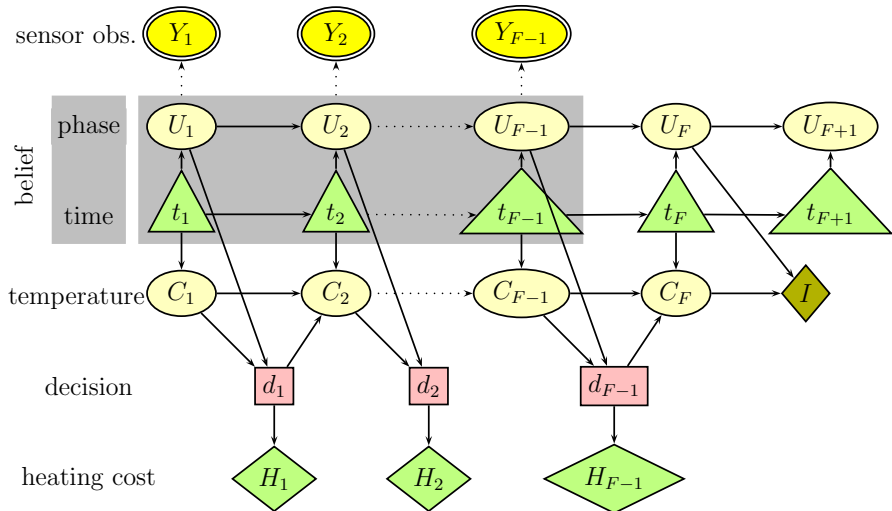
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# Approximate Solution

## Approximate POMDP solution

- **Markov Decision Process** - optimization for known phases
- Value Iteration Method
  - Optimize the total expected utility
  - w.r.t. phase number and floor-temperature
- **Greedy Strategies**

# MDP look-up decision table

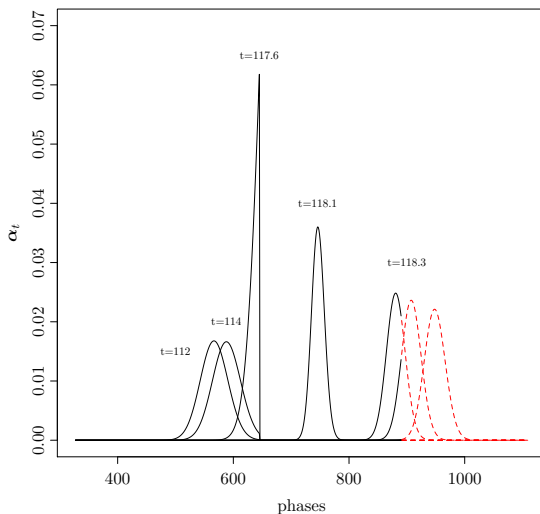
## Approximate POMDP Solution

Floor-temperature	Behavioural Phase	$\Delta Q^{(opt)}$	Decision <sup>(opt)</sup>
21	Phase-1		
21	Phase-2		
⋮	⋮		
21	Phase-1000		
22	Phase-1		
22	Phase-2		
⋮	⋮		
22	Phase-1000		
⋮	⋮		

\* $\Delta Q^{(opt)}$ : reward of heating

# Approximating to POMDP

Decision Vs Belief state for the given floor-temperature





# POMDP Greedy Strategies

- QMDP - expectation over all the phases

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- QMDP - expectation over all the phases
- Most likely phase
- Random phase
- Voting
- Random action

# POMDP Greedy Strategies

- **QMDP** - expectation over all the phases
- Most likely phase
- Random phase
- Voting
- Random action

\*Above greedy strategies return almost identical rewards.

# Robustness

## POMDP for Floor-heat Regulation Strategy

- Decision tool is **robust** to the changes in room temperature,

# Robustness

## POMDP for Floor-heat Regulation Strategy

- Decision tool is **robust** to the changes in room temperature, energy supply,



# Robustness

## POMDP for Floor-heat Regulation Strategy

- Decision tool is **robust** to the changes in room temperature, energy supply, mortality model

# Robustness

## POMDP for Floor-heat Regulation Strategy

- Decision tool is **robust** to the changes in room temperature, energy supply, mortality model and price of a piglet

# Robustness

## POMDP for Floor-heat Regulation Strategy

- Decision tool is **robust** to the changes in room temperature, energy supply, mortality model and price of a piglet
- POMDP strategy performed better than simple heuristic strategy especially when the room-temperature and energy supply was varied

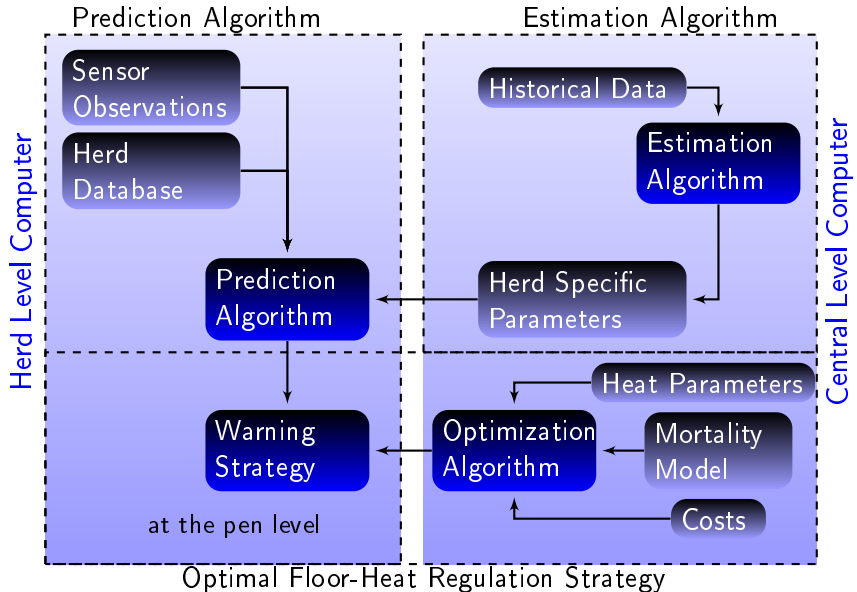
# Robustness

## POMDP for Floor-heat Regulation Strategy

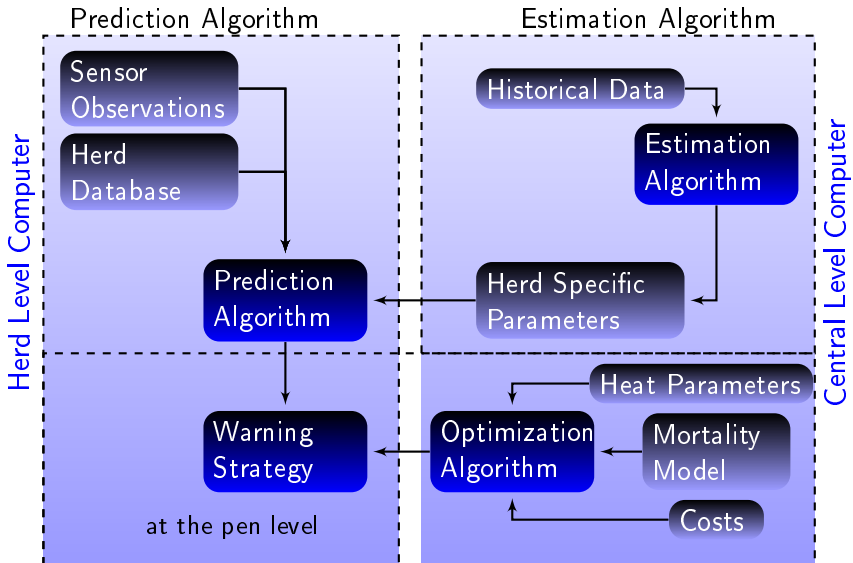
- Decision tool is **robust** to the changes in room temperature, energy supply, mortality model and price of a piglet
- POMDP strategy performed better than simple heuristic strategy especially when the room-temperature and energy supply was varied
- POMDP does not suggest to turn on the heater if it is not beneficial

# Final Remarks...

# Desired System - data management to decision



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Optimal Floor Heat Regulation Strategy

# Future works...

Studying the corners of the desired system



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- Including farmer's observation on farrowing into model

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### Studying the corners of the desired system

- Including farmer's observation on farrowing into model
- Improving the methods and the calculation speed of Estimation algorithm
- Similar decision support system for other applications

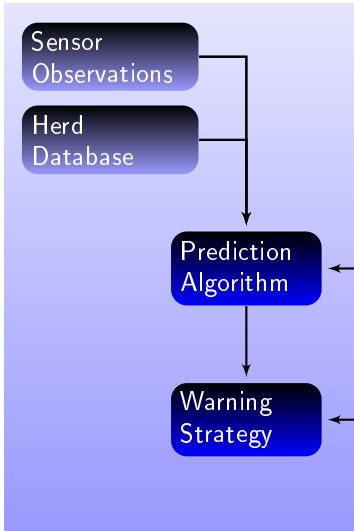
# Take home message...

## Contributions

- Framework of an automated system starting from data management to decision [The Intelligent Farrowing Pen](#)
- Model for monitoring the pre-parturition behaviour of an individual sow
- Prediction of onset of farrowing - can directly calculate the [expected time to farrowing](#) for an individual sow
- Prediction model as the kernel of a decision support system
- Modelling sows diurnal rhythm in sensor observations
- Integrating information from several sensors

# The Intelligent Farrowing Pen

Herd Level Computer



Central Level Computer

